

Systems, models and self-awareness

Toward a SysML model of consciousness



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- Systems engineering for conscious machines
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- On Model-based engineering
- The ASys vision of self-aware machines
- The Systems Modelling Language
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Systems engineering for conscious machines

The problems of Machine Consciousness

- We all know the many **problems of building conscious machines.**
- Let's summarise them in two big ones:

1 We don't know/agree on **what “consciousness” is**

2 We don't know **how to build the thing** (in part because of 1)

Building conscious machines

- To construct conscious machines we can use two major strategies (as described by Holland some time ago): direct and incremental
 - **Direct** approaches: try to build a machine following a particular theory of consciousness (e.g. GWT).
 - **Incremental** approaches: try to add competencies one-at-a-time up to reaching the level of consciousness.
- No matter what is the approach, MC will suffer a receding-horizon phenomenon similar to AI (there is not a ultimate test procedure)

Building conscious machines: the idea

BEHAVIORAL AND BRAIN SCIENCES (2004) 27, 377–442
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The emulation theory of representation: Motor control, imagery, and perception

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Abstract: The *emulation theory of representation* is developed and explored as a framework that can revealingly synthesize a variety of representational functions of the brain. The framework is based on constructs from control theory (forward models, processing (Kalman filters). The idea is that in addition to simply engaging with the body and environment, the brain constructs circuits that act as models of the body and environment. During overt sensorimotor engagement, these models are driven by copies in parallel with the body and environment, in order to provide expectations of the sensory feedback, and to enhance sensory information. These models can also be run off-line in order to produce imagery, estimate outcomes of different actions, and develop motor plans. The framework is initially developed within the context of motor control, where it has been shown that inner models running in parallel with the body can reduce the effects of feedback delay problems. The same mechanisms of motor imagery as the off-line driving of the emulator via efference copies. The framework is extended to account for visual perception as the off-line driving of an emulator of the motor-visual loop. I also show how such systems can provide for amodal spatial perception, including visual perception, results from such models being used to form expectations of, and to interpret, sensory information by briefly outlining other cognitive functions that might also be synthesized within this framework, including reasoning, the phenomena, and language.

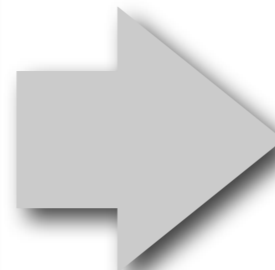
Keywords: efference copies; emulation theory of representation; forward models; Kalman filters; motor control; motor imagery; perception; visual imagery

1. Introduction

The idea that one of the central tasks performed by the brain is to internally model various brain-external elements and processes is not new. In the twentieth century, Kenneth Craik was one of the most explicit proponents of this view (Craik 1943). In various guises the view has been taken up

emerged. In providing such a structure, I hope to contribute to both of these areas of research by providing a framework within which various results can be synthesized, and within which a number of issues can be more clearly so as to avoid certain kinds of errors.

The emulation framework I will articulate not only provides a great deal of motor control and motor imagery



```
/*
 * Assume there are three processes: Pa, Pb, and Pc. Only Pa can output
 * the letter A, Pb B, and Pc C.
 * Utilizing only semaphores (and no other variables) the processes are
 * synchronized so that the output satisfies the following conditions:
 */

import Utilities.*;
import Synchronization.*;

class Pa extends ABCs implements Runnable { // extend ABCs to
                                           // access semaphore sum

    public void run () {
        while (true) { nap(1+(int)(random(500)));
            System.out.print("A"); System.out.flush();
            V(sum);
        }
    }
}

class ABCs extends MyObject {

    protected static final BinarySemaphore B // these semaphores
        = new BinarySemaphore(0);           // are static
    protected static final BinarySemaphore C // so subclasses
        = new BinarySemaphore(1);           // Pa, Pb,
    protected static final CountingSemaphore sum // and Pc share
        = new CountingSemaphore(0);         // them

    public static void main(String[] args) {

        Thread pa = new Thread(new Pa());
        Thread pb = new Thread(new Pb());
        Thread pc = new Thread(new Pc());
        pa.start(); pb.start(); pc.start();
        nap(9000);
        pa.stop(); pb.stop(); pc.stop();
        System.out.println();
        System.out.println("B=" + B + ", C=" + C + ", sum=" + sum);
        System.exit(0);
    }
}

class Pb e
    public
    while
    P
    S
    V
}
}
```


Building conscious machines: the reality

COGNITIVE AND BRAIN SCIENCES (2004) 27, 377–442
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Emulation theory of representation: Motor control, imagery, and perception

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The emulation theory of representation is developed and explored as a framework that can revealingly synthesize the representational functions of the brain. The framework is based on constructs from control theory (forward models, Kalman filters). The idea is that in addition to simply engaging with the body and environment, the brain constructs internal models of the body and environment. During overt sensorimotor engagement, these models are driven by sensory feedback from the body and environment, in order to provide expectations of the sensory feedback, and to enhance action. These models can also be run off-line in order to produce imagery, estimate outcomes of different action plans, and to develop motor plans. The framework is initially developed within the context of motor control, where it has been shown that running in parallel with the body can reduce the effects of feedback delay problems. The same mechanisms of imagery as the off-line driving of the emulator via efference copies. The framework is extended to account for visual perception, and the driving of an emulator of the motor-visual loop. I also show how such systems can provide for amodal spatial imagery, and how visual perception, results from such models being used to form expectations of, and to interpret, sensory input. I also outline other cognitive functions that might also be synthesized within this framework, including reasoning, the sense of agency, and language.

Conclusion

emerged. In providing such a structure, I hope to provide a framework within which various results can be synthesized, and to provide a framework within which a number of issues can be more clearly articulated, so as to avoid certain kinds of errors.

The emulation framework I will articulate not only provides a framework for a great deal of motor control and motor imagery, but also provides a framework for a great deal of perception and imagery.



```
/*
 * Assume there are three processes: Pa, Pb, and Pc.
 * the letter A, Pb B, and Pc C.
 * Utilizing only semaphores (and no other variables)
 * synchronized so that the output satisfies the requirements.
 */

import Utilities.*;
import Synchronization.*;

class Pa extends ABCs implements Runnable { // e
//

    public void run () {
        while (true) { nap(1+(int)(random(500)));
            System.out.print("A"); System.out.flush();
            V(sum);
        }
    }
}

class ABCs extends MyObject {

    protected static final BinarySemaphore A
        = new BinarySemaphore(0);
    protected static final BinarySemaphore B
        = new BinarySemaphore(1);
    protected static final CountingSemaphore C
        = new CountingSemaphore(0);

    public static void main(String[] args) {

        Thread pa = new Thread(new Pa());
        Thread pb = new Thread(new Pb());
        Thread pc = new Thread(new Pc());
        pa.start(); pb.start(); pc.start();
        nap(9000);
        pa.stop(); pb.stop(); pc.stop();
        System.out.println();
        System.out.println("B=" + B + " ");
        System.exit(0);
    }
}
```

Magic of the consciousness engineer



Towards a Positive Theory of Consciousness (I)

- There are too many basic understandings of what consciousness is: process, function, module, property, emergent phenomenon, quantum state, etc.
- The problem can be traced back to a common architectural reverse-engineering problem: the **extraction of function from non-formal description of architectures.**
- A rapid scan of the literature on the topic leaves the following impressions:
 - Most theories that target the whole thing seem just literature (or plain rubbish, or love & hate manifestations)
 - Positive theories are mostly seem as partial and naïve

Towards a Positive Theory of Consciousness (II)

- We need a unified theory of “consciousness”:
 - That targets the whole thing (i.e. even qualia)
 - That is widely agreed across disciplines
 - That is expressible in different abstraction levels to be at the same time
 - general and
 - precise and
 - verifiable

Generality



Precision

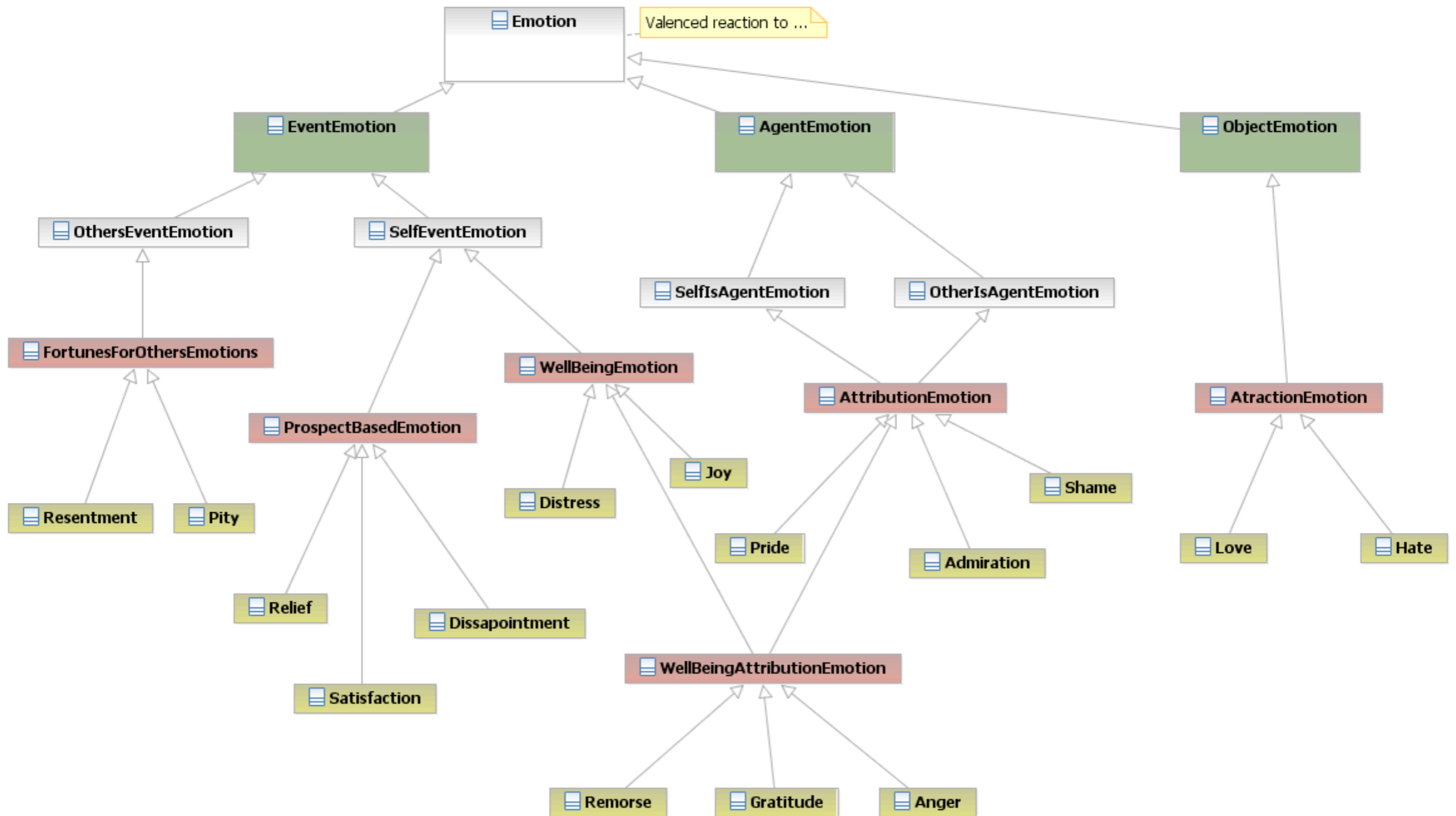
Towards a Positive Theory of Consciousness (III)

- We must **express the theory in a formal enough language** as to minimise the problem of multiple interpretations
- Some approaches to “formal theories” are available but are far from being accepted as targeting the whole (e.g. Tononi’s)
- Some other approaches are just incomprehensible (e.g. Zelzenikar’s).
- There’s even some researchers that think that formalisation of consciousness is untenable
- But ... **this is a necessary step in science.**

Modes of expression

- Verbal-Linguistic
 - Sharing words, writings, documents
 - Why are we stuck here?
- Logical-Mathematical
 - Equations, drawings, MatLab models
 - Engineering/scientific disciplinary
- Graphic-Visual
 - Pictures, charts, drawings
 - Used by many people!
- There are other methods too...

Ortony et al. emotions



Rationale for a Systems Approach to Consciousness

- The recognition of the enormous complexity of the issue of building conscious machines points into a direction that can help solve both problems.
- Complex systems engineering is addressed using the methods of the so-called discipline of "Systems Engineering"
- This sits in the middle of technical and managerial issues, addressing the multifaceted problems of large-scale, complex systems engineering
- In this work we propose the use of recent systems engineering modelling methods to address the complexities of MC theorising

Core Objective

- The core objective of this approach is the development of **Reference Models of Consciousness**
- Aim:
 - Consolidate a unified vision on consciousness functions and mechanisms
 - To organise knowledge about consciousness components into standardised, reusable and extensible models
 - To develop methods for (re-)using this knowledge in support of the construction of conscious systems

The Nature of Models

“Modeling, in the broadest sense, is the cost-effective use of something in place of something else for some cognitive purpose.

...

A model represents reality for the given purpose; the model is an abstraction of reality in the sense that it cannot represent all aspects of reality. This allows us to deal with the world in a simplified manner, avoiding the complexity, danger and irreversibility of reality.”

[Rothemberg-1989]

Reference Models of Consciousness Approach

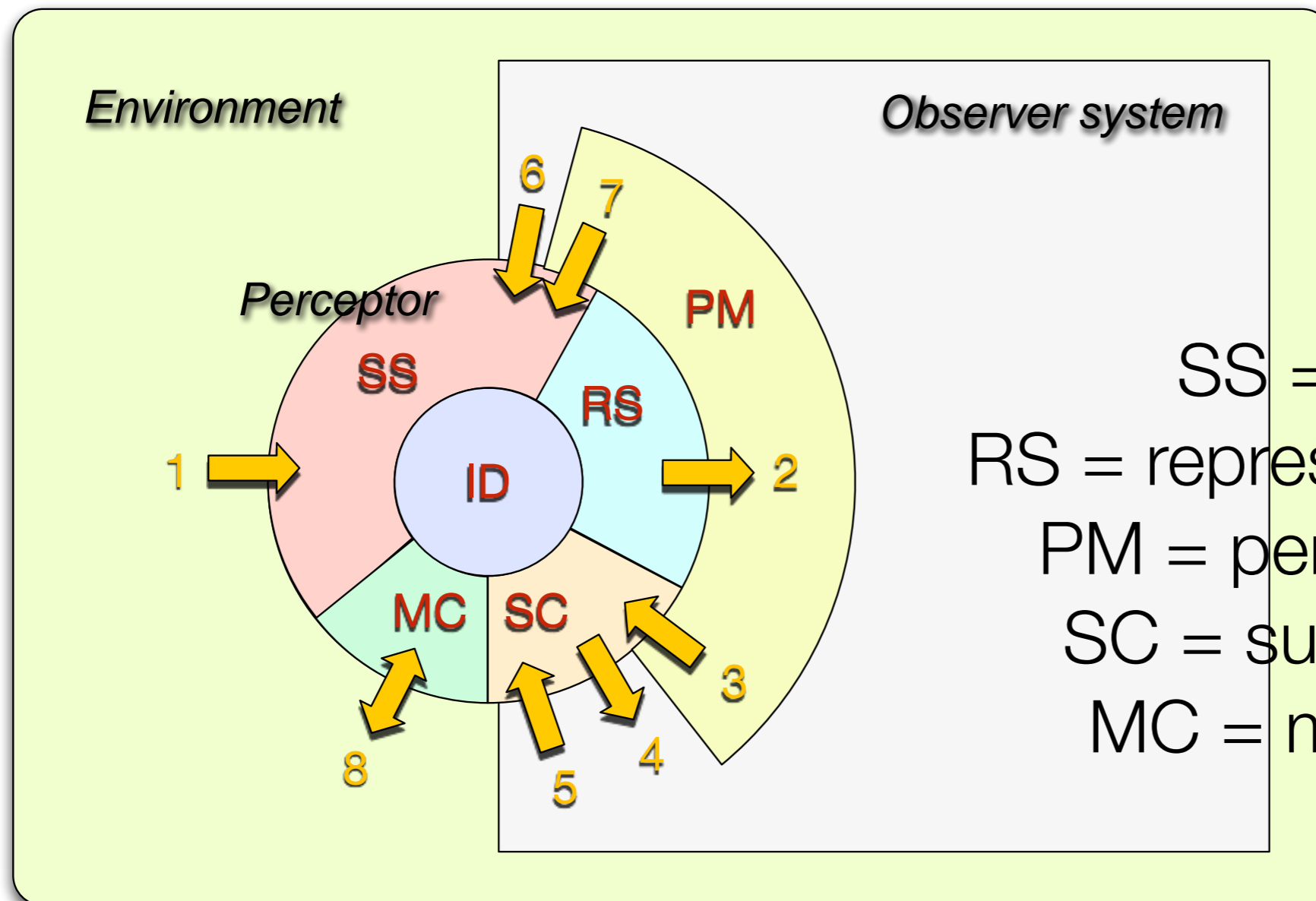
- Method:
 - Define an ontology for describing consciousness components and systems
 - Define reference models as standardised elements that include knowledge and information about the form, function and behaviour of components
 - Formalise the ontology and reference models in SysML
 - Create semantic mappings between SysML, cognitive science, systems biology and engineering tools

Targetting the two problems at once

- This approach can not only address problem 1 (**what “consciousness” is**) but can also help with problem 2 (**how to build the thing**)
- This can be possible by the unification of
 - the emerging model-based theory of consciousness and
 - the modern model-based practice of embedded systems construction
- Let's see some of the bricks of this approach

On Model-based minds

The question of perception

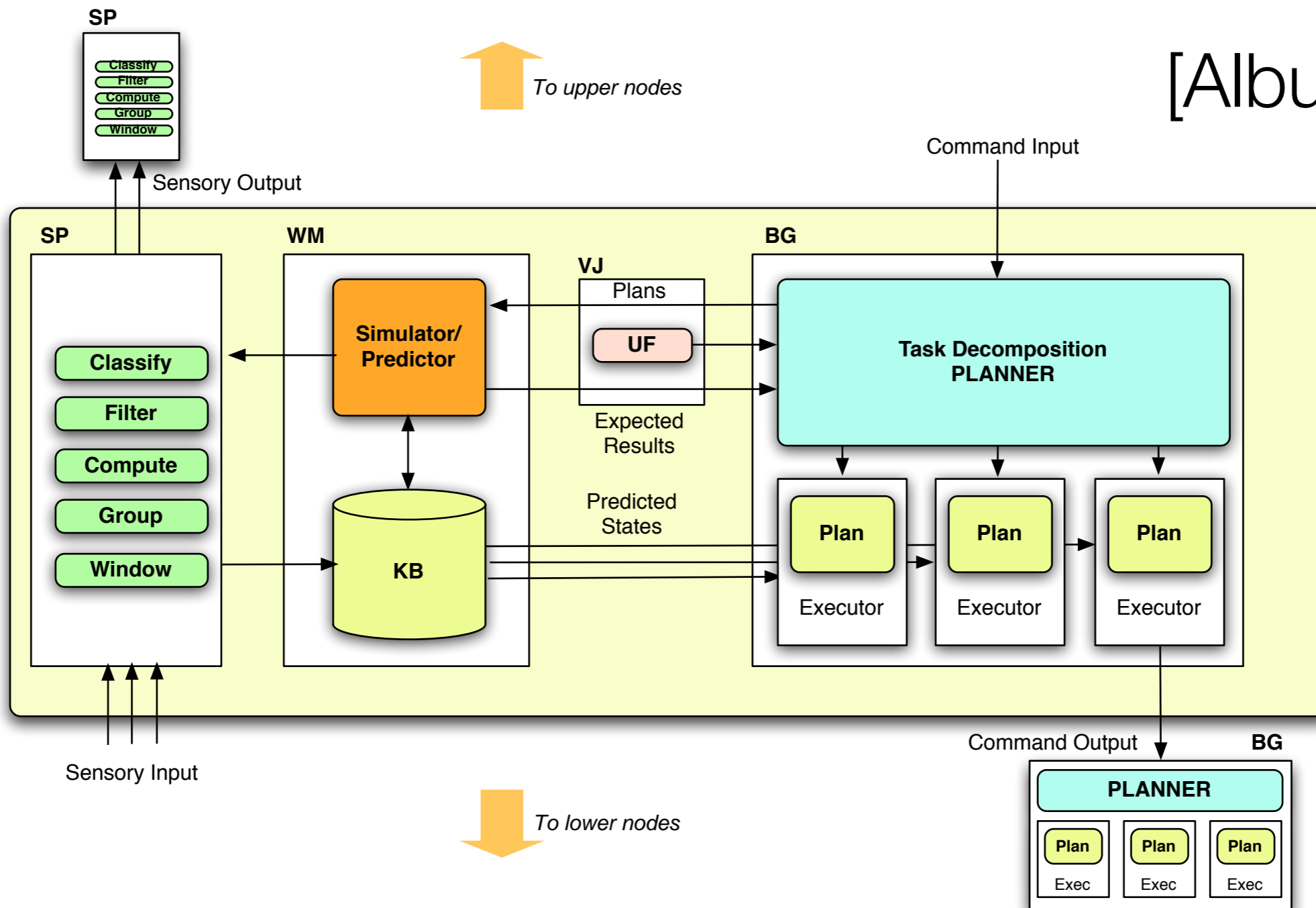


SS = sensory system
RS = representation system
PM = perceptual memory
SC = substratal coupling
MC = marginal coupling

[López 2007]

The question of action

[Albus 1999]



The question of Knowledge?

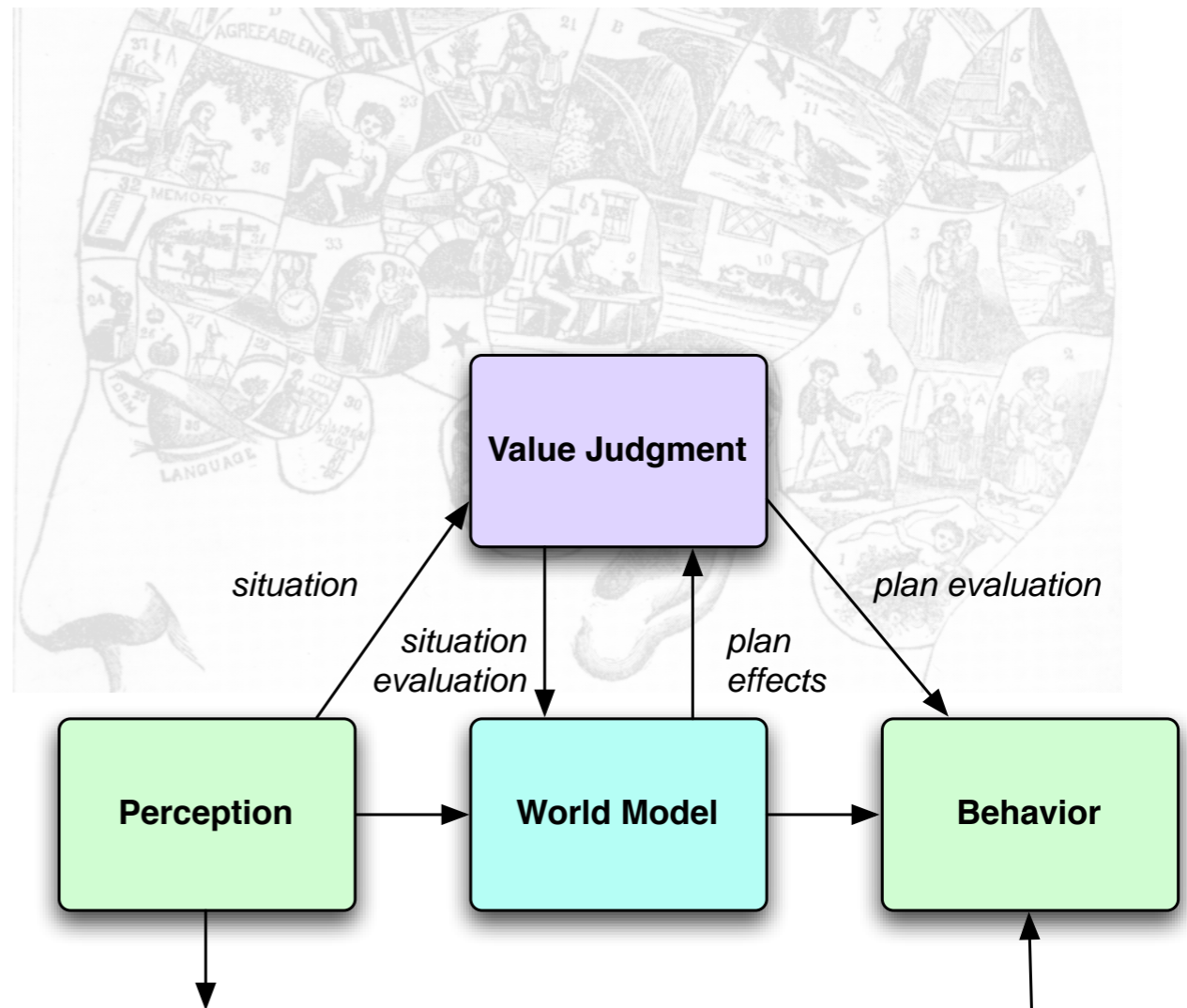
- Knowledge is composed by ***executable dynamic models***
 - Models about some (partial) reality in/out the agent
 - that may be executed
 - Over a physical ***execution engine*** (e.g. cerebellum)
 - Over a virtual machine running over a physical execution engine or another virtual machine
- May be degenerated (e.g. a simple static value)
- May be embodied (aka “*precompiled*” with the execution engine)
- May be shared among heterogeneous engines

The end of the questioning

- This can be summarised in a single sentence:

Minds are model-based controllers

- They can be direct/inverse, implicit/explicit, static/dynamic, isolated/coupled, “genetic”/”memetic”/learned, homogeneous/heterogeneous, postdictive/predictive, etc.



On Model-based systems engineering

What is Systems Engineering?

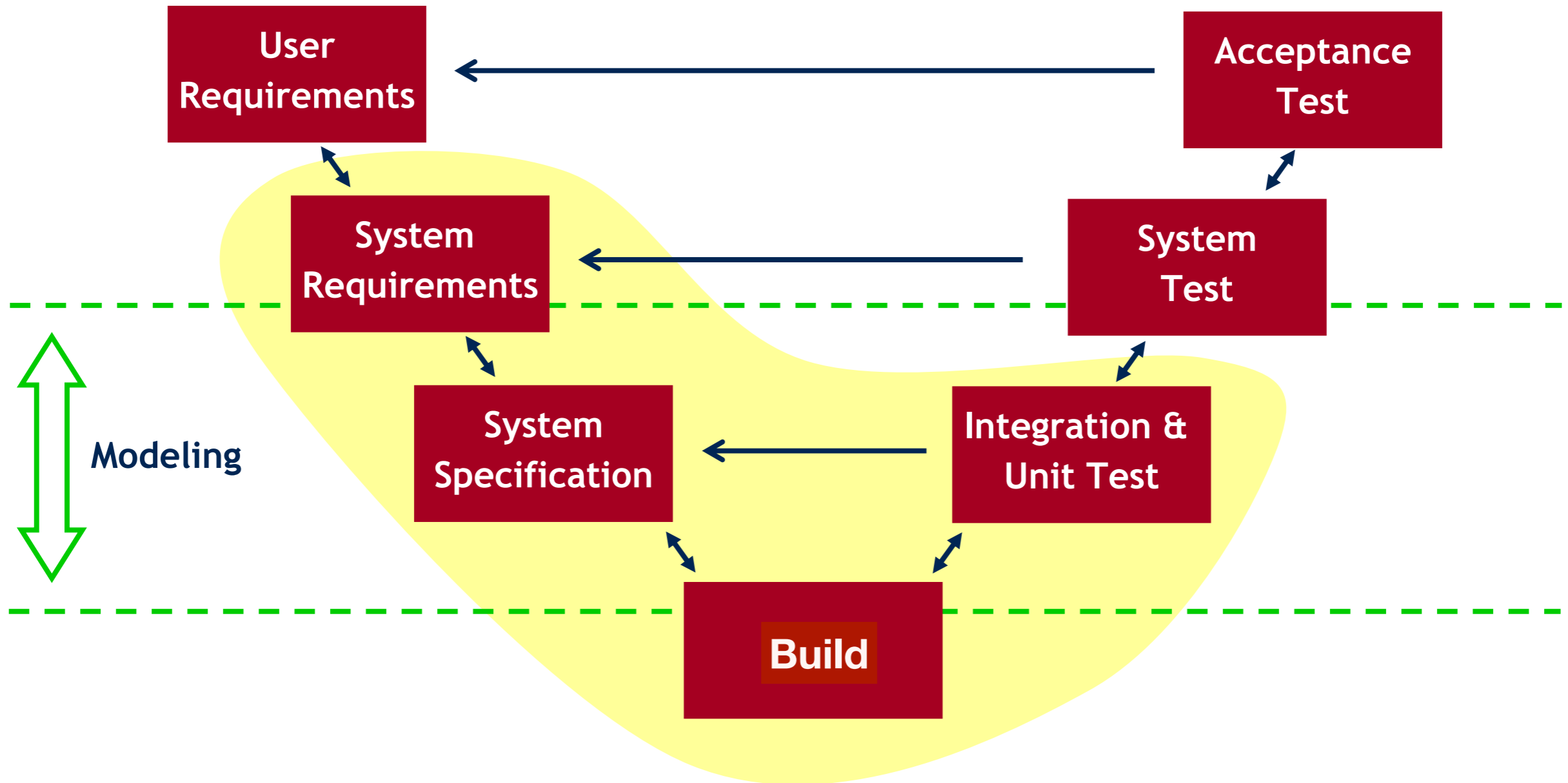
Systems Engineering is an interdisciplinary approach and means to enable the realisation of successful systems.

It focuses on defining customer needs and required functionality early in the development cycle, documenting requirements, then proceeding with design synthesis and system validation while considering the complete problem.

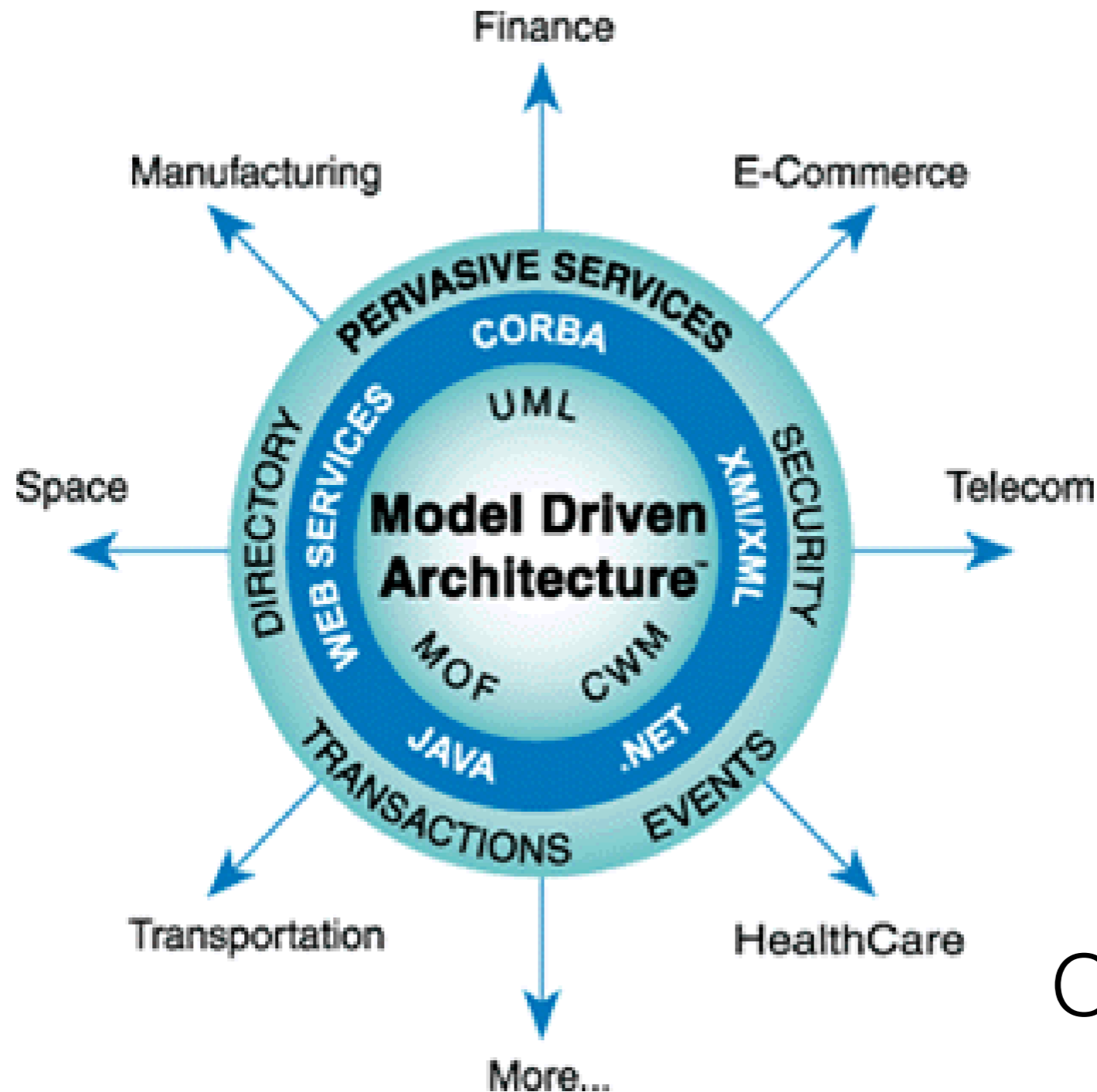
Does this match our needs?

- Talking about “customers” and “needs” may seem far-off for research on machine consciousness.
- In this field we can identify three classes of global research objectives for MC:
 - Building machines like us (the C3PO drive)
 - Understanding biological consciousness
 - Building better machines (the misgone HAL dream)
- All them specify needs for our realisations and SE is a systematic way of addressing those needs (aka requirements)

The V-model of Development

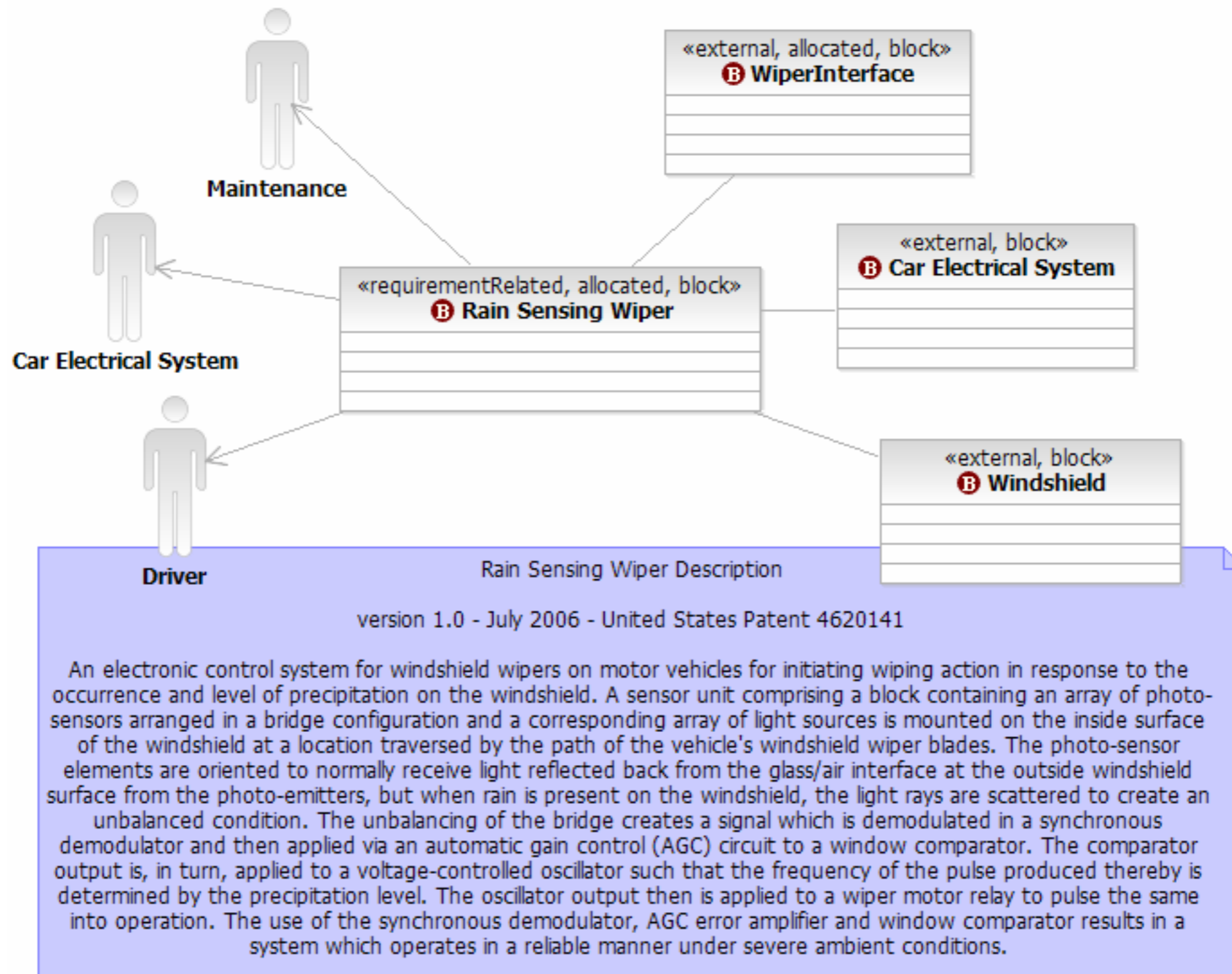


A Focus on Software and Architecture



OMG's **MDA**

Context diagram for autonomous wiper



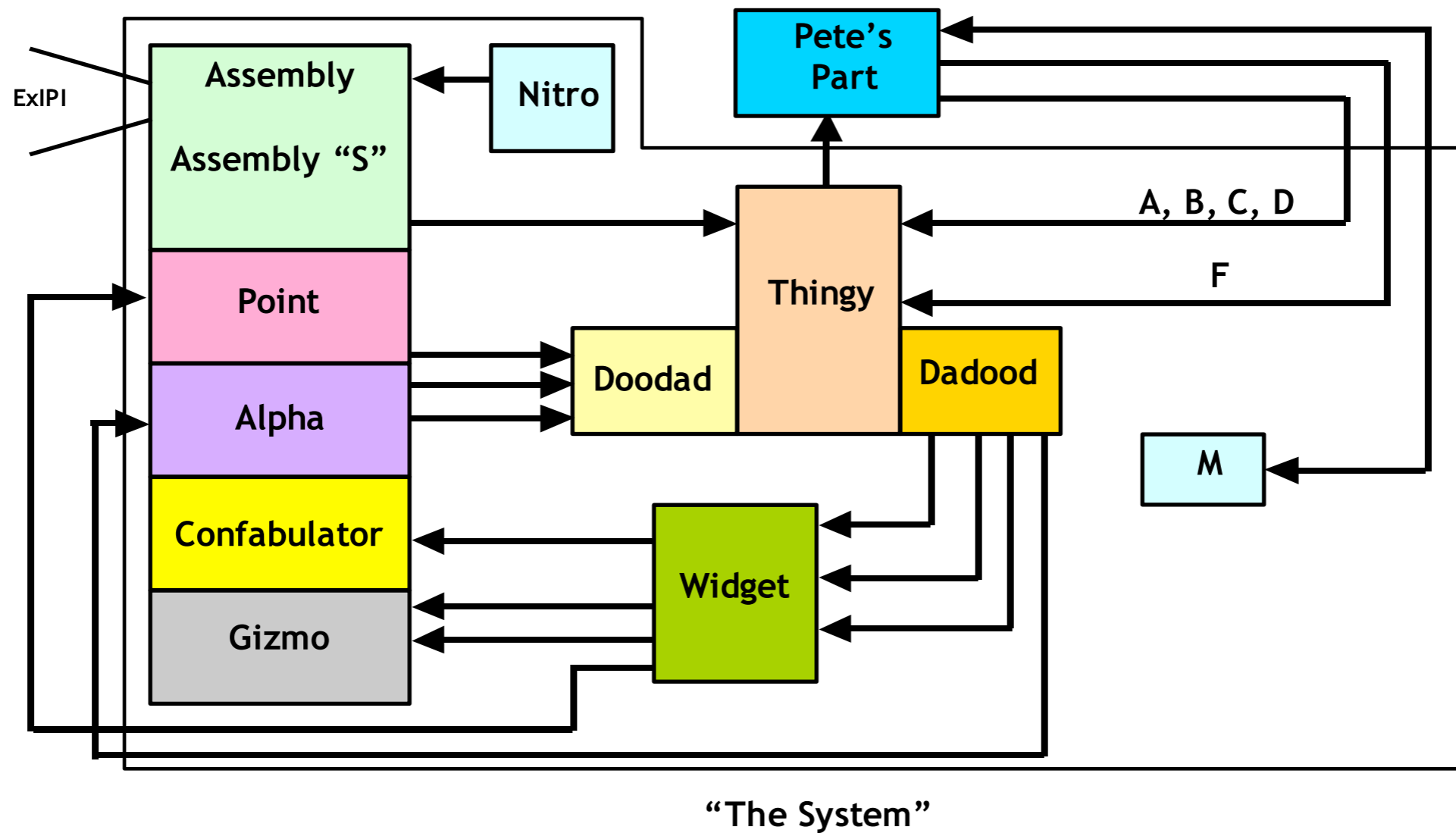
A Text Model

of complex systems by means of scalable design patterns. This approach is specially well captured in the multiresolutional approach fostered by the control design pattern that Meystel calls the *elementary loop of functioning* (Meystel, 2003). Of importance in relation with the ASys theory of meaning is the incorporation of value judgment mechanisms over this elementary loop (see Figure 7).

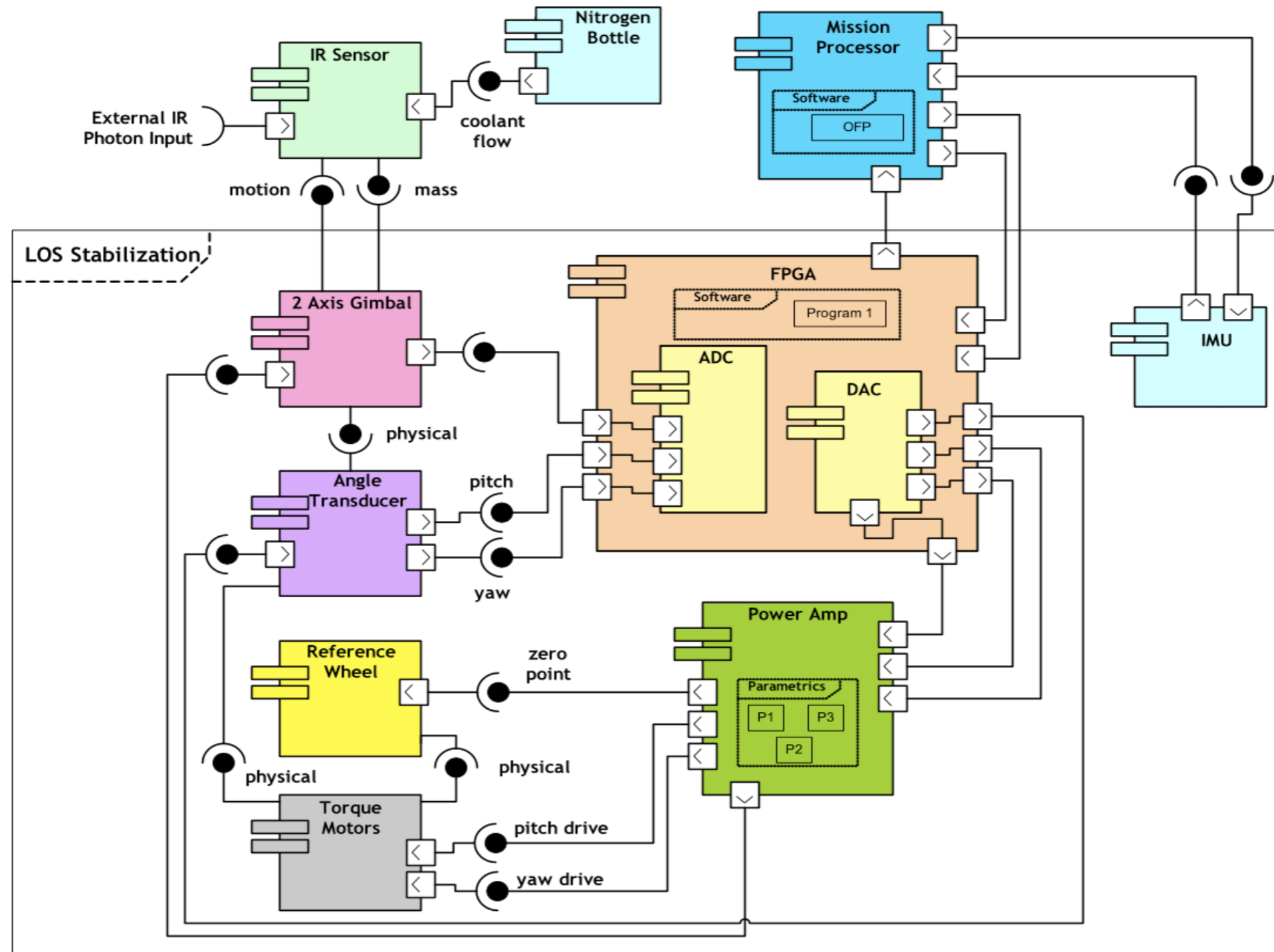
The elementary loop of functioning, when applied hierarchically, generates a multiresolutional ladder of meanings specifically focused on the controllable subspace of each control level. This approach partitions both the problem of meaning generation and the problem of action determination, leading to hierarchical control structures that have interesting properties of self-similarity.

This core design pattern approach is extended in the concept of a control node of the RCS control architecture (Albus, 1992) (see Figure 7). Beyond the model of the world and the sensing and acting units, this architecture considers the existence of a value judgment unit that evaluate both static states and dynamic states derived from hypothetical plan execution.

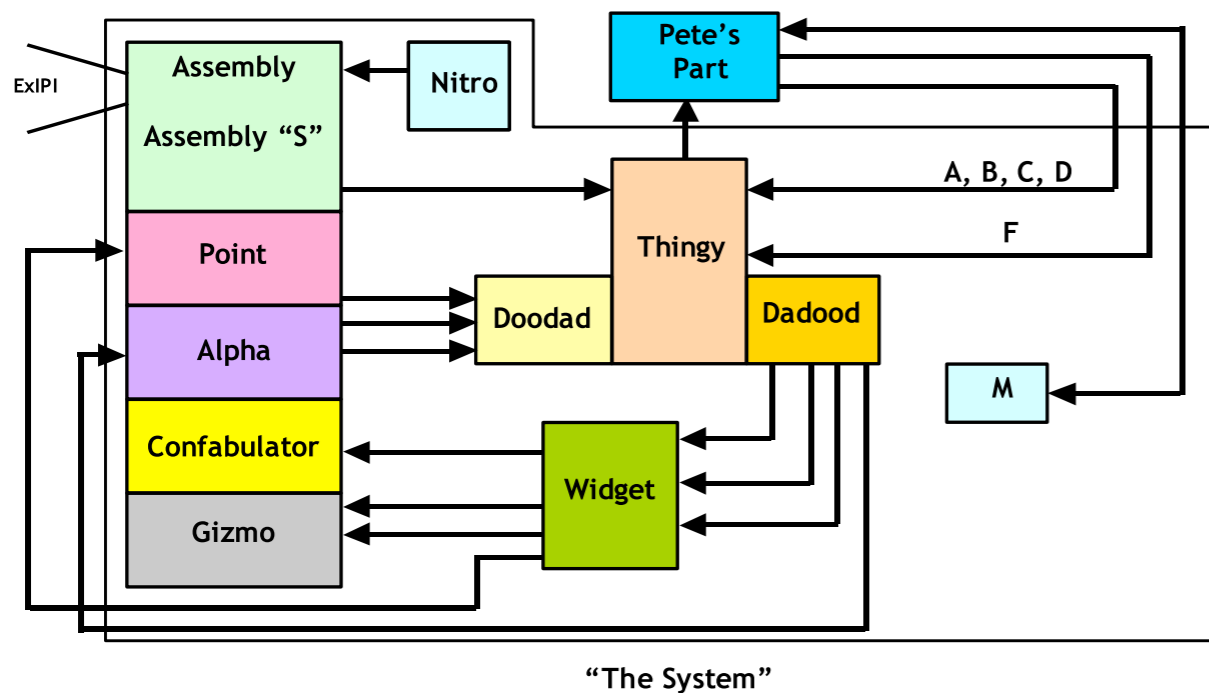
A (soft) block model



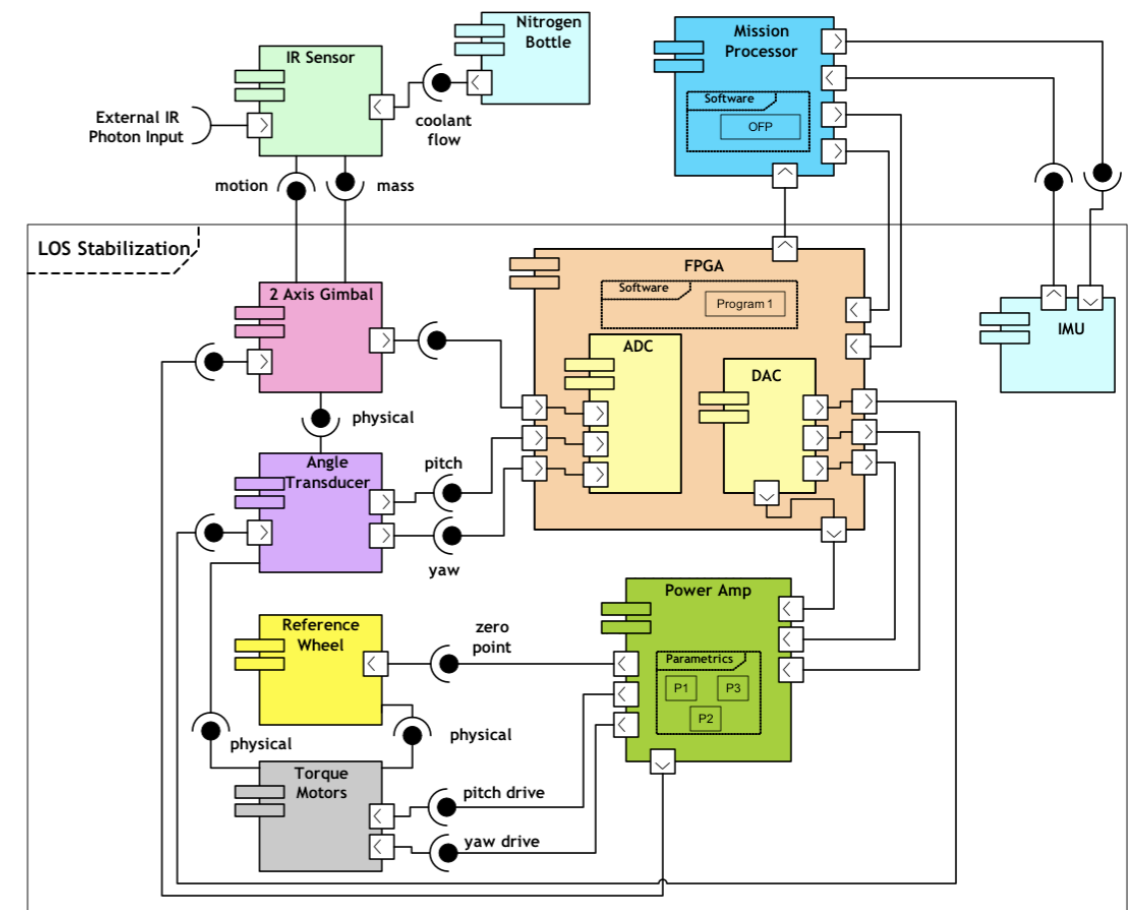
A semi-formal block model



Compare and Contrast



Block diagram with random or inconsistent meaning to symbols



Component diagram with well-defined syntax and grammar

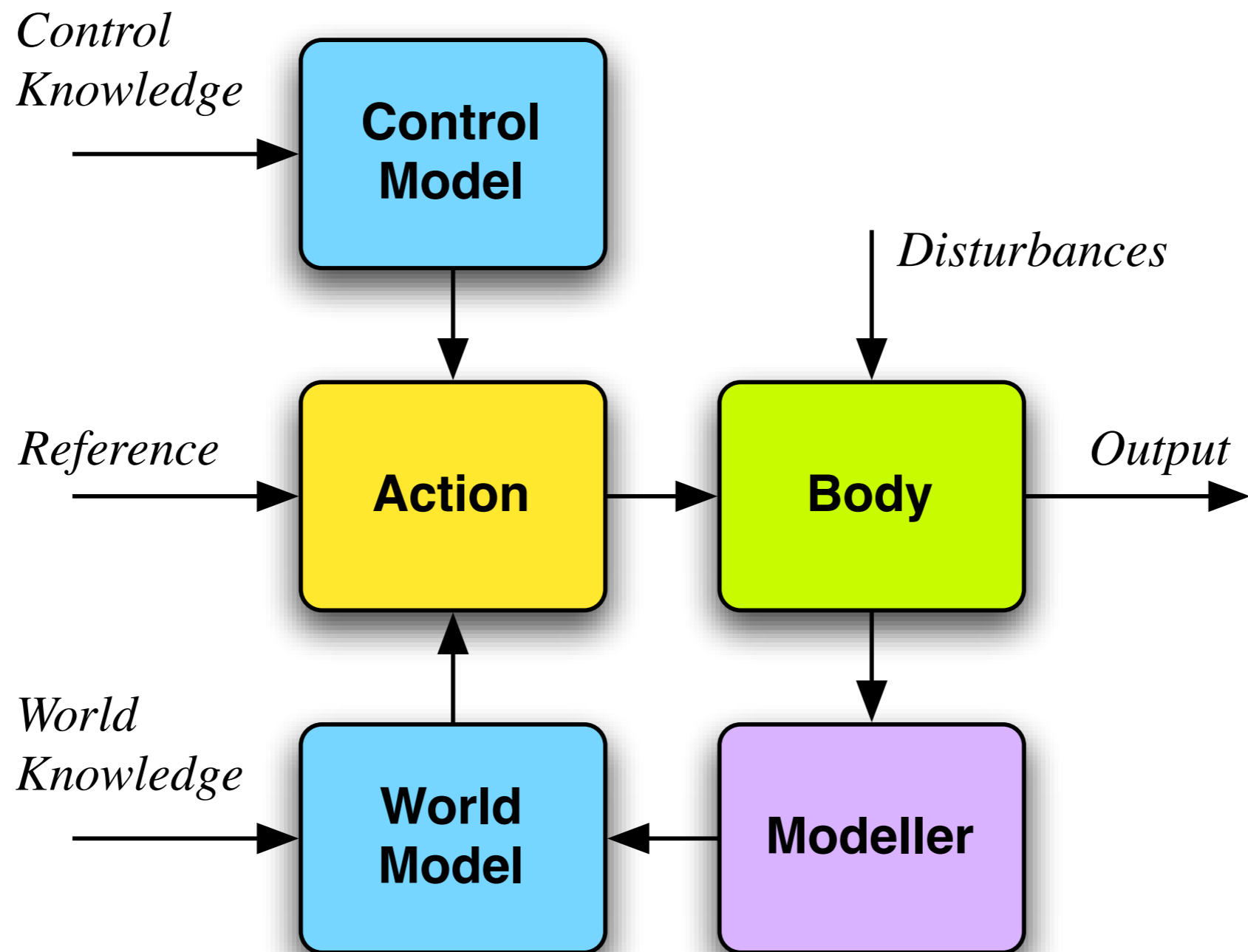
Communication is key !

The engineer (scientist) must use a consistent, well-defined, and well-understood language to communicate the requirements and design to other stakeholders (engineers or not), otherwise the product will be questionable, founder, fail, or be a full disaster.

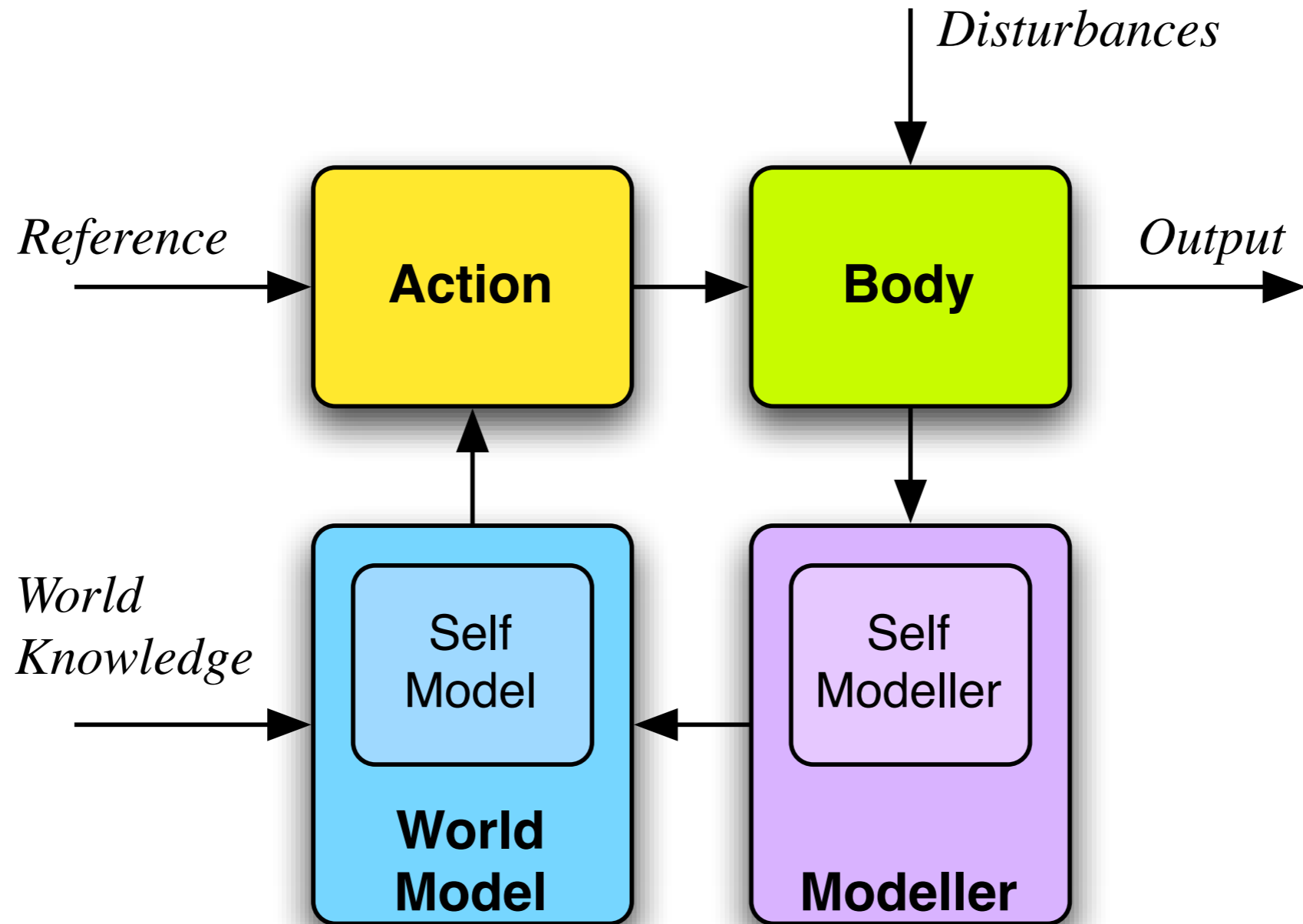
For the systems engineer, that language is currently SysML.

The ASys vision of self-aware machines

Expliciting Models



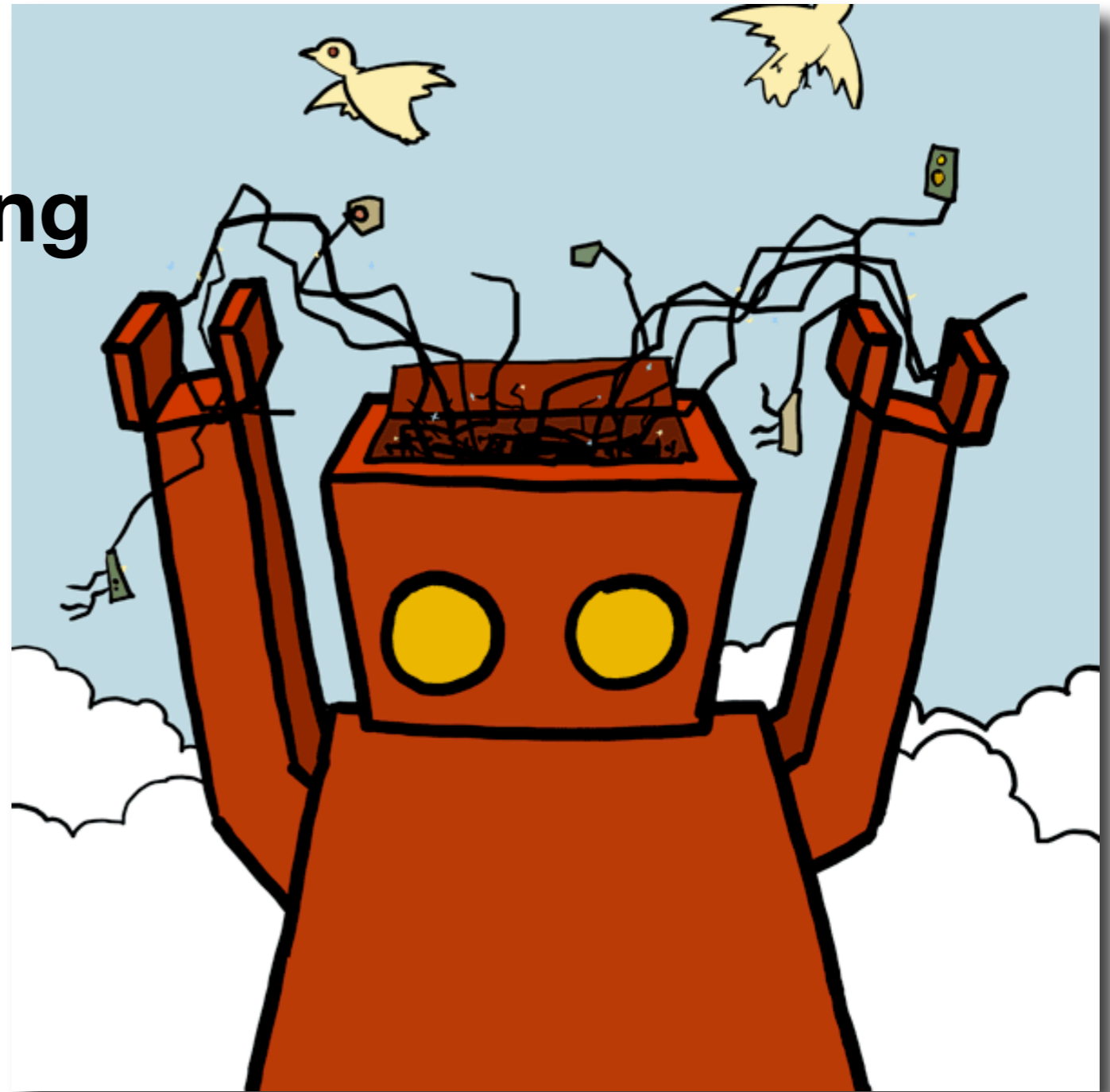
The 'Self' Step



Self = Access to Self-implementation

By means of **model-integrated engineering** of the system itself

Use the very
engineering models
as run-time
self-models



Principles

- **Model-based cognition:** A cognitive system exploits models of other systems in their interaction with them.
- **Model isomorphism.** An embodied, situated, cognitive system is as good performer as its models are.
- **Anticipatory behavior.** Except in degenerate cases, maximal timely performance is achieved using predictive models.

Principles

- **Unified cognitive action generation.** Generate action based on an integrated, scalable, unified model of task, environment and self in search for global performance maximisation.
- **Model-driven perception.** Perception is realised as the continuous update of the integrated models used by the agent in a model-based cognitive control architecture by means of real-time sensorial information.

Principles

- **System awareness.** An aware system is continuously perceiving and generating meaning -future value- from the continuously updated models.
- **System self-awareness/consciousness.** A conscious system is continuously generating meanings from continuously updated self-models in a model-based cognitive control architecture.

The Systems Modelling Language

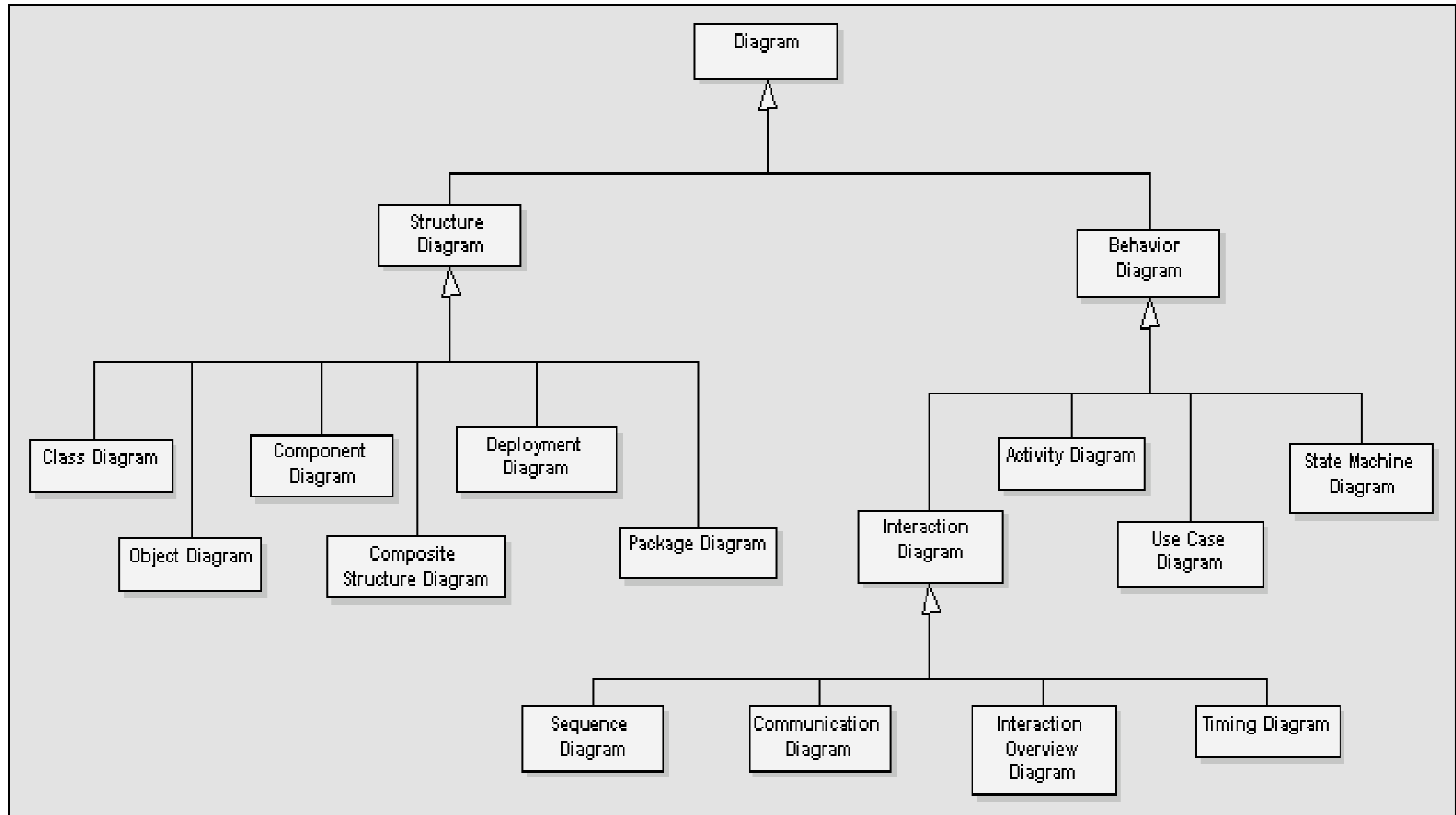
What is the Systems Modeling Language ?

- A model language for holistic system representation and systems engineering
- A graphical/textual semi-formal modeling language addressing the issues of the Systems Engineering RFP developed by the OMG, INCOSE, and AP233
- Can be seen as a UML Profile that represents a subset of UML 2 with extensions
- Supports the specification, analysis, design, verification and validation of systems that include hardware, software, data, personnel, procedures, and facilities

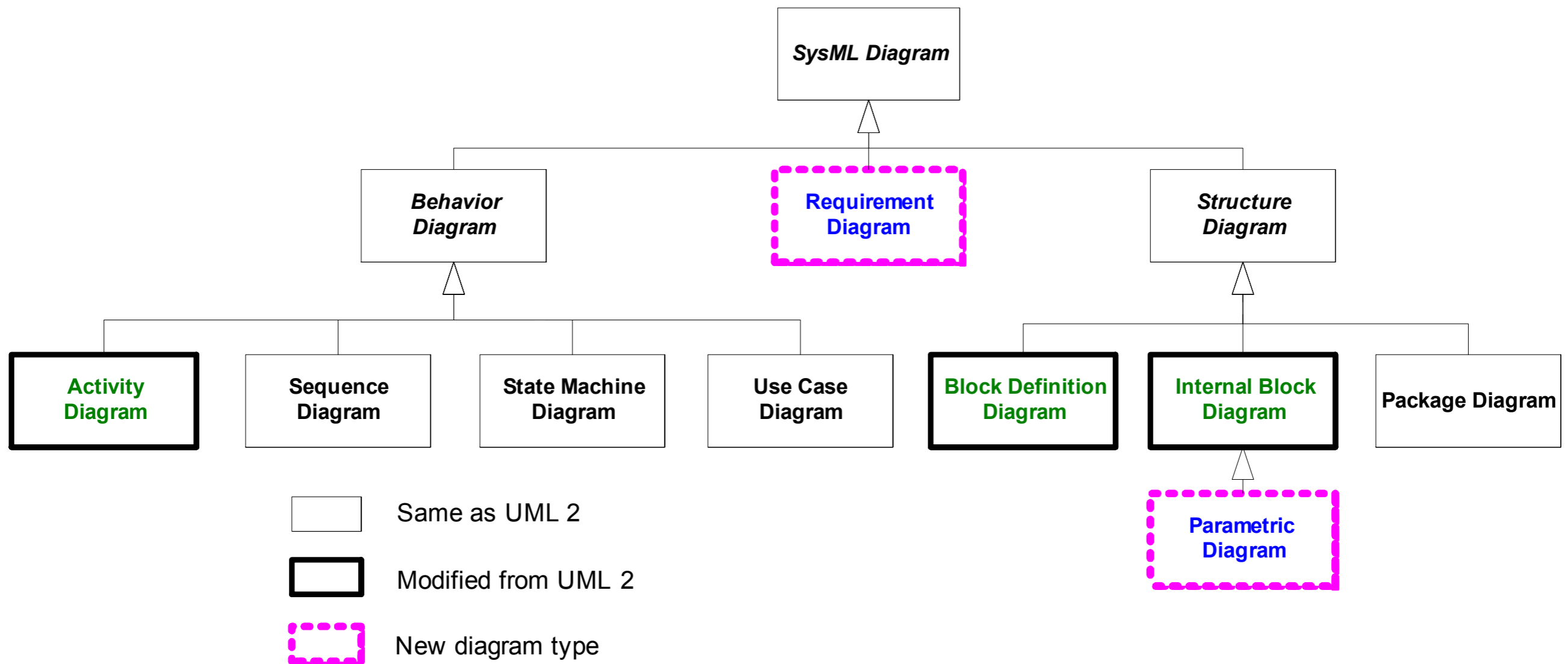
Some aspects of SysML

- SysML is broader than software-centric modelling languages
- Can capture all salient aspects of complex system design
- Is quite intuitive for system engineers
- Supporting proven systems engineering concepts like requirements, hierarchical block structuring and parametrics
- The language has been designed to not be a barrier to traditional system engineering methods

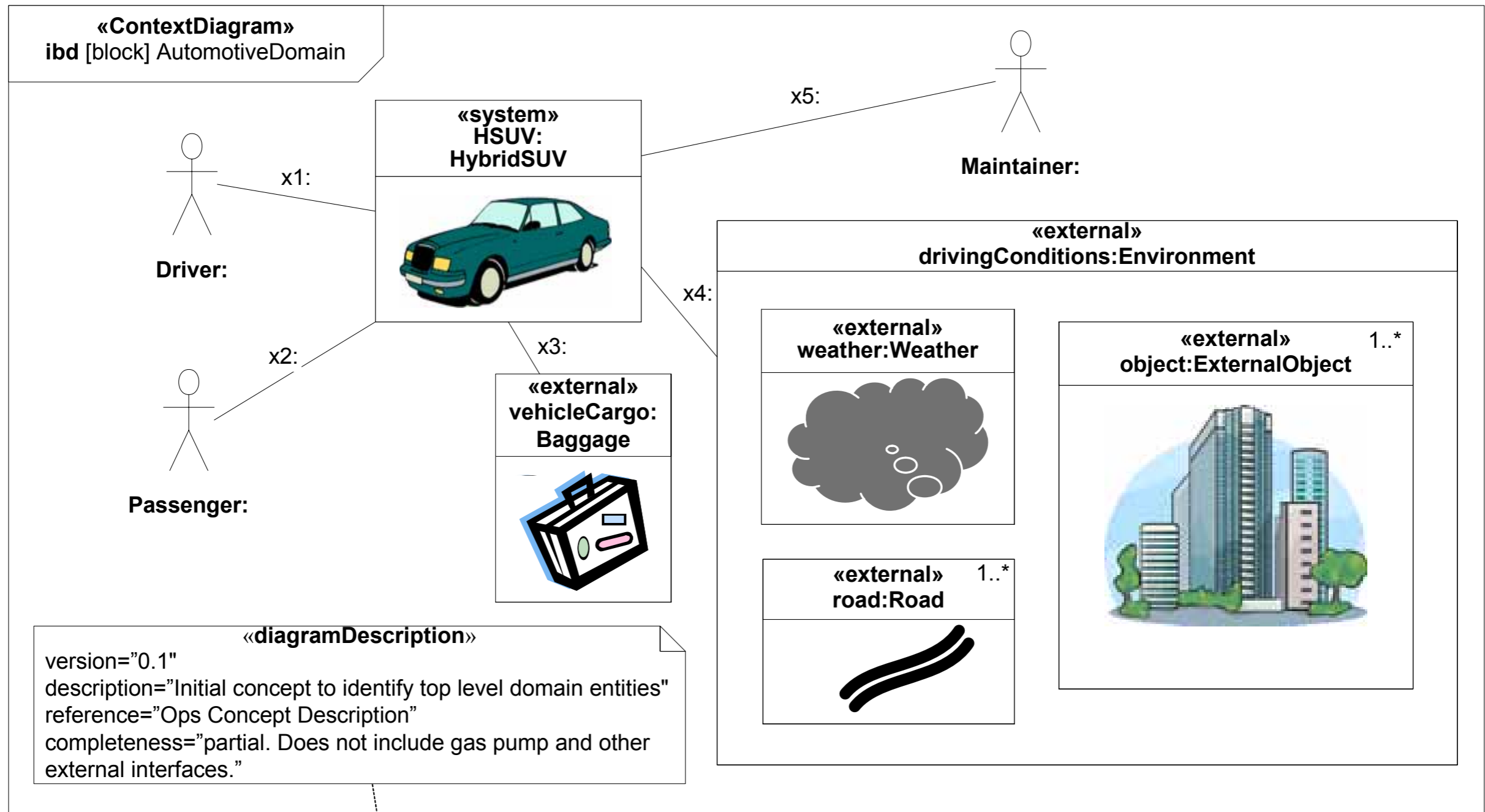
UML 2 Diagrams



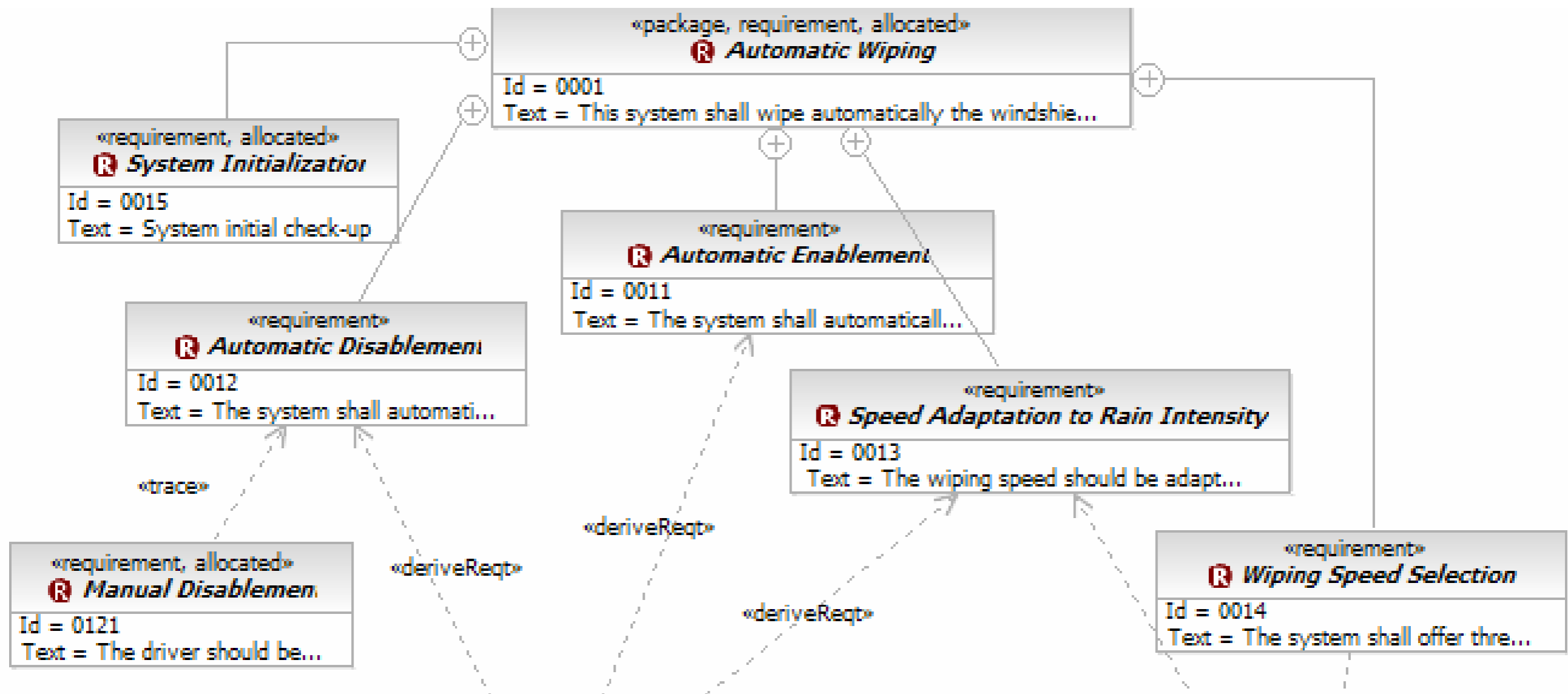
SysML Diagrams



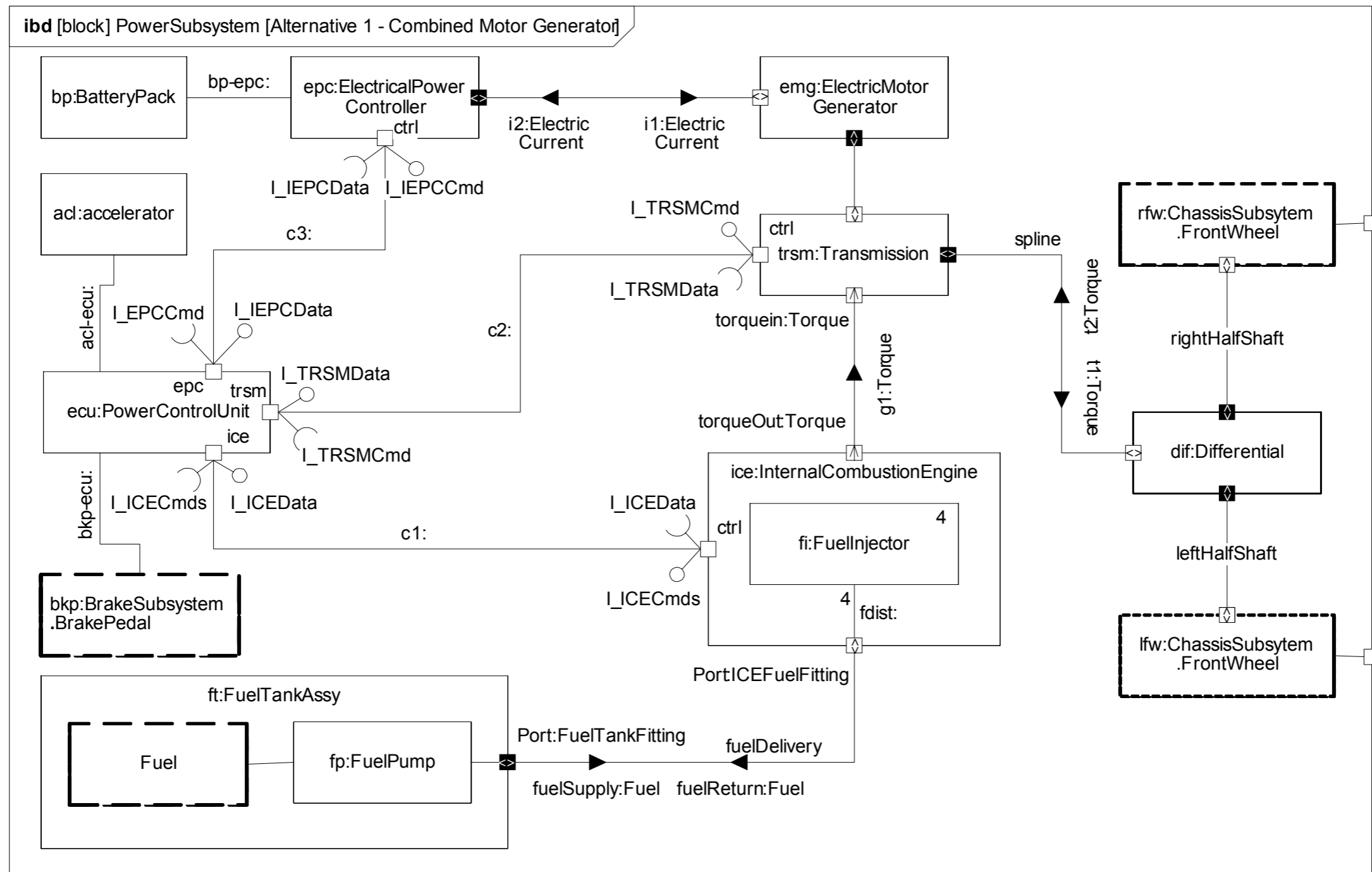
Context diagram for a vehicle



Requirements diagrams



Internal Block Diagram



SysML Drawing Summary

SYSML DIAGRAM	PURPOSE	UML ANALOG
Activity diagram	Show system behavior as control and data flows. Useful for functional analysis. Compare Extended Functional Flow Block diagrams (EFFBDs), already commonly used among systems engineers.	Activity diagram
Block Definition diagram	Show system structure as components along with their properties, operations and relationships. Useful for system analysis and design.	Class diagram
Internal Block diagram	Show the internal structures of components, including their parts and connectors. Useful for system analysis and design.	Composite Structure diagram
Package diagram	Show how a model is organized into packages, views and viewpoints. Useful for model management.	Package diagram
Parametric diagram	Show parametric constraints between structural elements. Useful for performance and quantitative analysis.	N/A
Requirement diagram	Show system requirements and their relationships with other elements. Useful for requirements engineering.	N/A

SysML Drawing Summary (II)

Sequence diagram	Show system behavior as interactions between system components. Useful for system analysis and design.	Sequence diagram
State Machine diagram	Show system behavior as sequences of states that a component or interaction experience in response to events. Useful for system design and simulation/code generation.	State Machine diagram
Use Case diagram	Show system functional requirements as transactions that are meaningful to system users. Useful for specifying functional requirements. (Note potential overlap with Requirement diagrams.)	Use Case diagram
Allocation tables* *dynamically derived tables, not really a diagram type	Show various kinds of allocations (e.g., requirement allocation, functional allocation, structural allocation). Useful for facilitating automated verification and validation (V&V) and gap analysis.	N/A

Towards a SysML model of consciousness

Systemic Machine Consciousness?

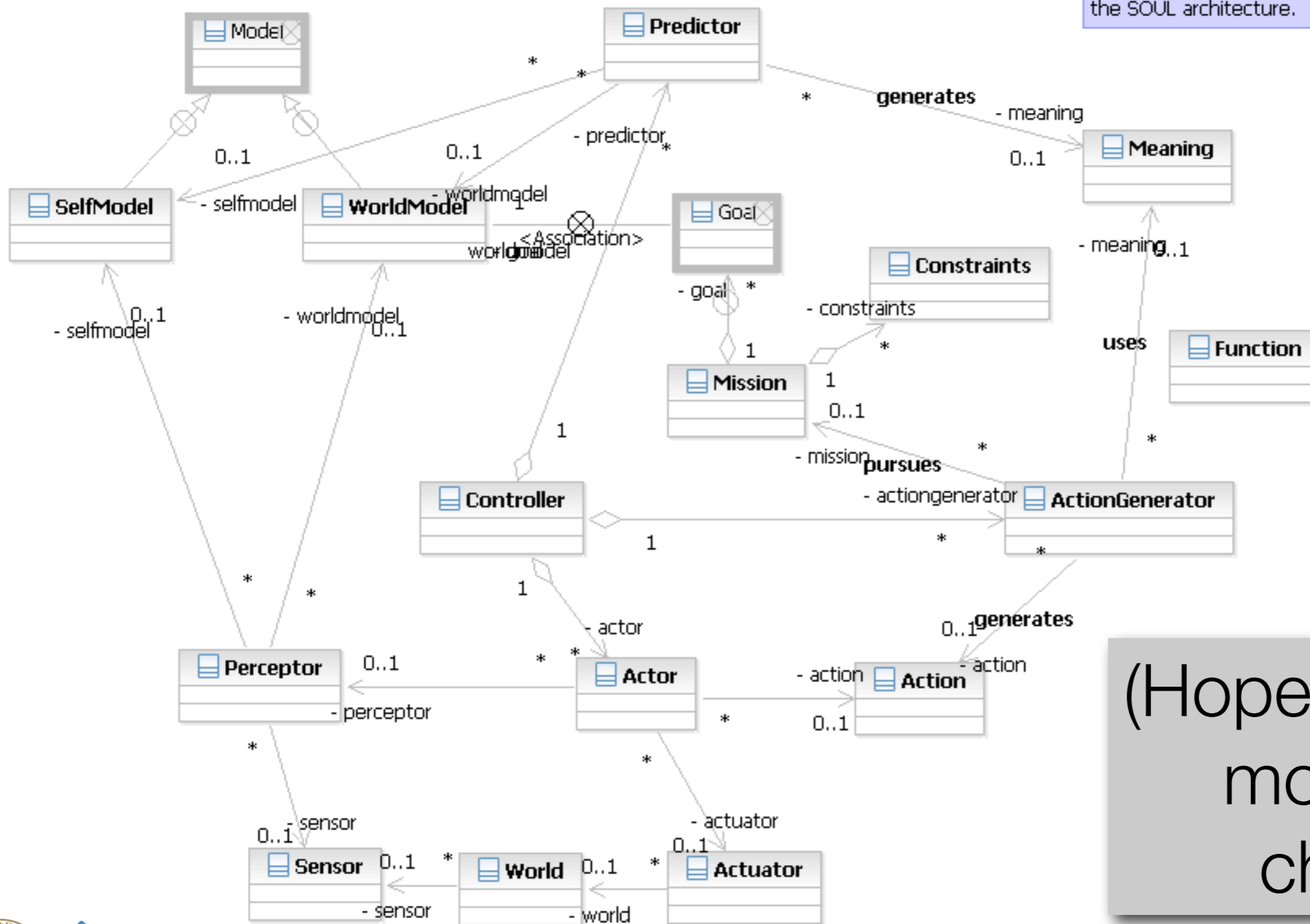
- The approach based on model-based systems engineering can be described as **explicit model-based, reflective, predictive, adaptive** autonomous systems engineering.
- The key is using the engineering models as self-models
- The major value is that autonomous control based on self-models enables an **increased awareness** that can lead to more **robust performance**
- Provides a road to both 1) expressing an unified theory of consciousness and 2) using it to build machines

An ongoing work

- This is an **ongoing work** being developed in the ICEA/C3 projects
- The focus is the construction of an architecture for self-awareness based on
 - A deep engineering model of self-awareness
 - A model-based construction process based on this engineering model
 - An architecture for model-based autonomous systems exploiting these models

The Present State

The purpose of this model is to depict the major structures in the SOUL architecture.



(Hopefully Initial) modelling chaos !



The tooling: Rational Systems Developer

The screenshot displays the Rational Systems Developer SysML Modeling environment. The main workspace shows a class diagram with the following elements:

- Classes:** Organization, ObjectiveStructure, DirectivenessMechanism, Purposive, and a partially visible class on the left.
- Associations:**
 - Organization to ObjectiveStructure: labeled "changes" and "corresponds".
 - ObjectiveStructure to Organization: labeled "variable_part_of".
 - DirectivenessMechanism to ObjectiveStructure: labeled "modifies".
- Notes:**
 - A yellow note above Organization: "As system's properties or dependencies among elements and couplings. Really in here? Organization attached to an instant, therefore not at metamodel level?"
 - A yellow note next to ObjectiveStructure: "NOTE: Objective as global state of system and environment. However, particular objectives for the System".

The interface includes a Project Explorer on the left showing a hierarchical structure of models and diagrams. The bottom section shows the Properties window for the selected class, "ProcessModel::Main", with fields for Name, Type, and Description.

The ongoing modelling effort

«requirement»
R OriginalStatement
Id = S0.0
Text = Describe an Amygdala partial model by LARAL that reproduces the results of (Hatfield 1996), about amygdala's role in first and second order conditioning.
-First order conditioning (stimulus-response association) is realised by LA and CeA
-Second order conditioning (stimulus-stimulus association) is realised within BLA

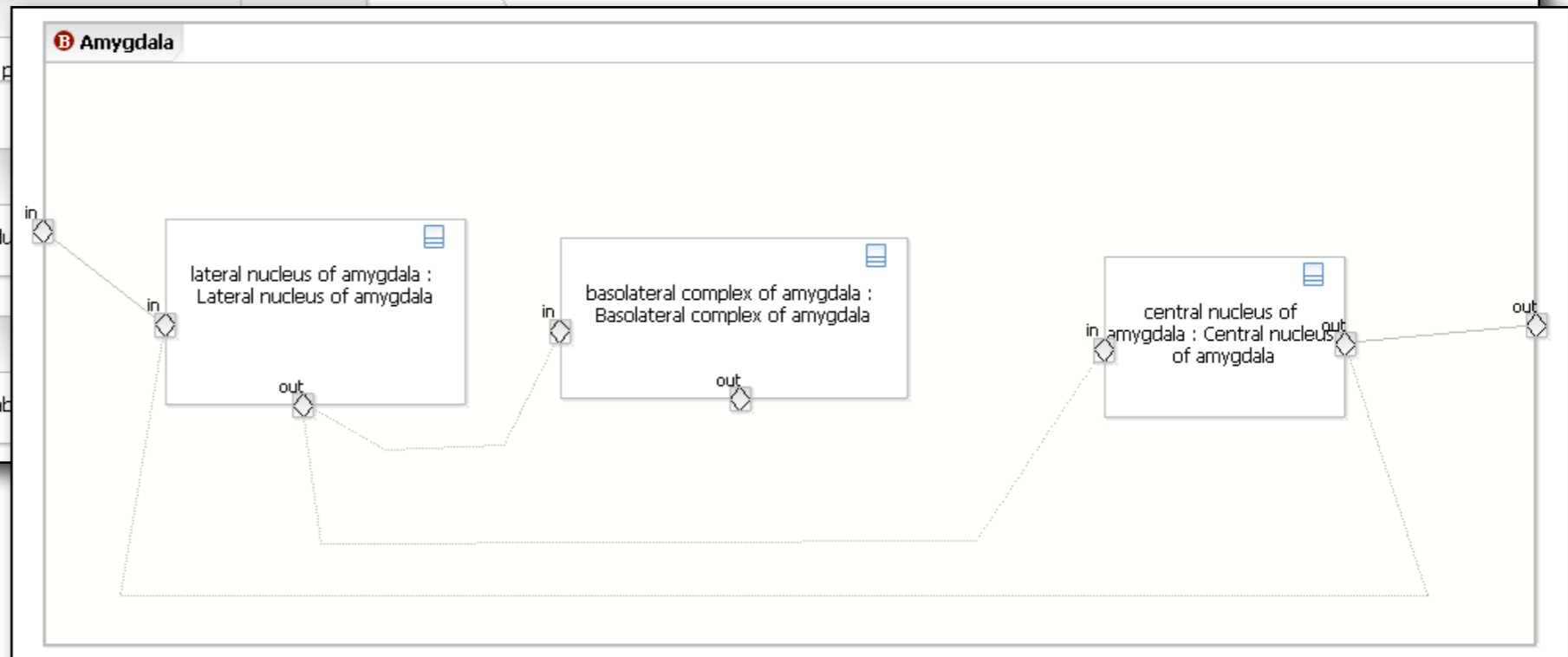
«requirement»
R 1stOrderConditioning
Id = S1.0
Text = The system must learn to produce for a certain stimulus "s1" a response "r" if "s1" usually occurs previously to a rewarding stimulus "rs" which the system associates to "r"

«refine»

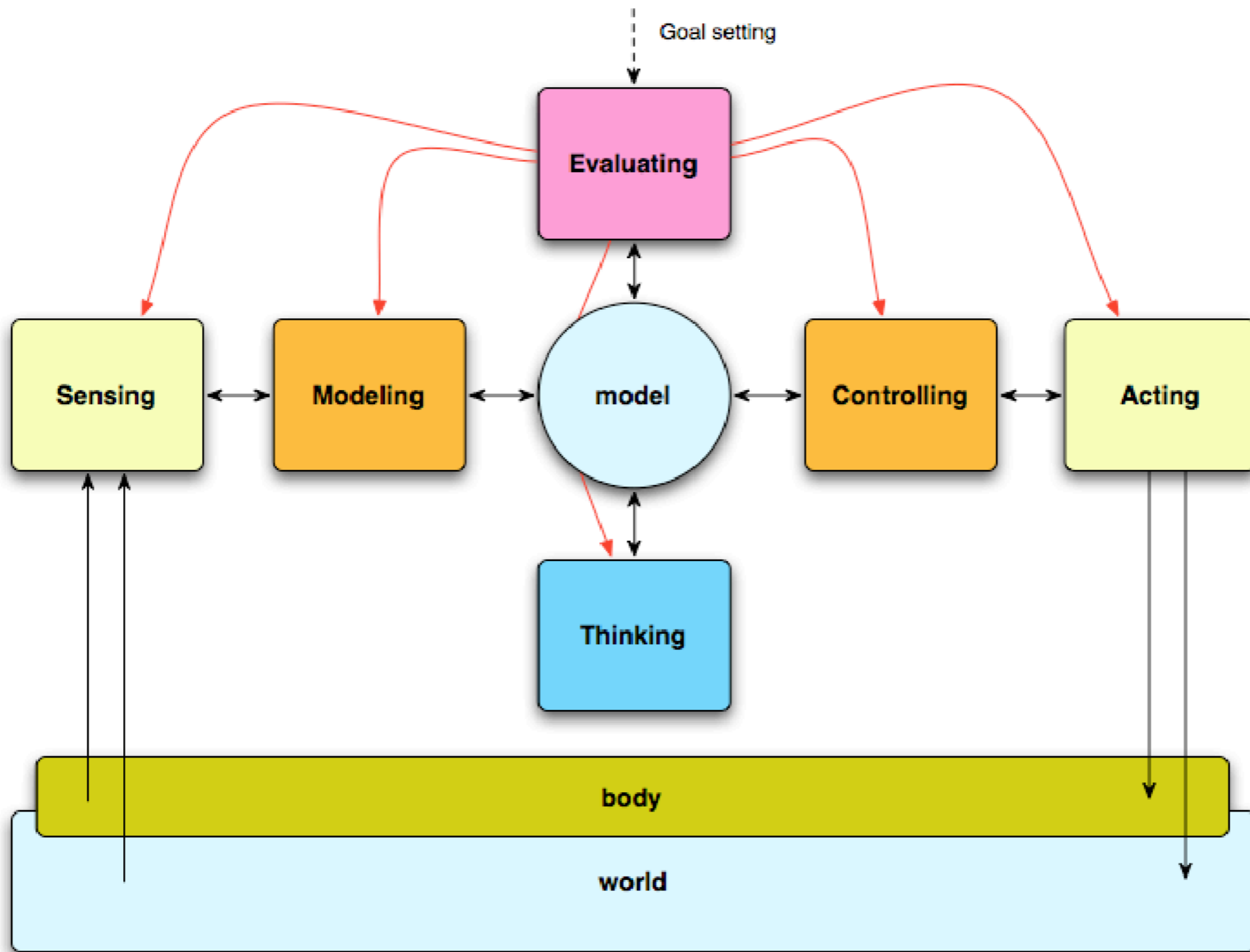
«requirement»
R LearningActivation
Id = S1.1
Text = Each time, and only then, a response "r" is generated, the stimulus p

Id = S2.0
Text = The system must produ

Id = S3.0
Text = The system must be ab

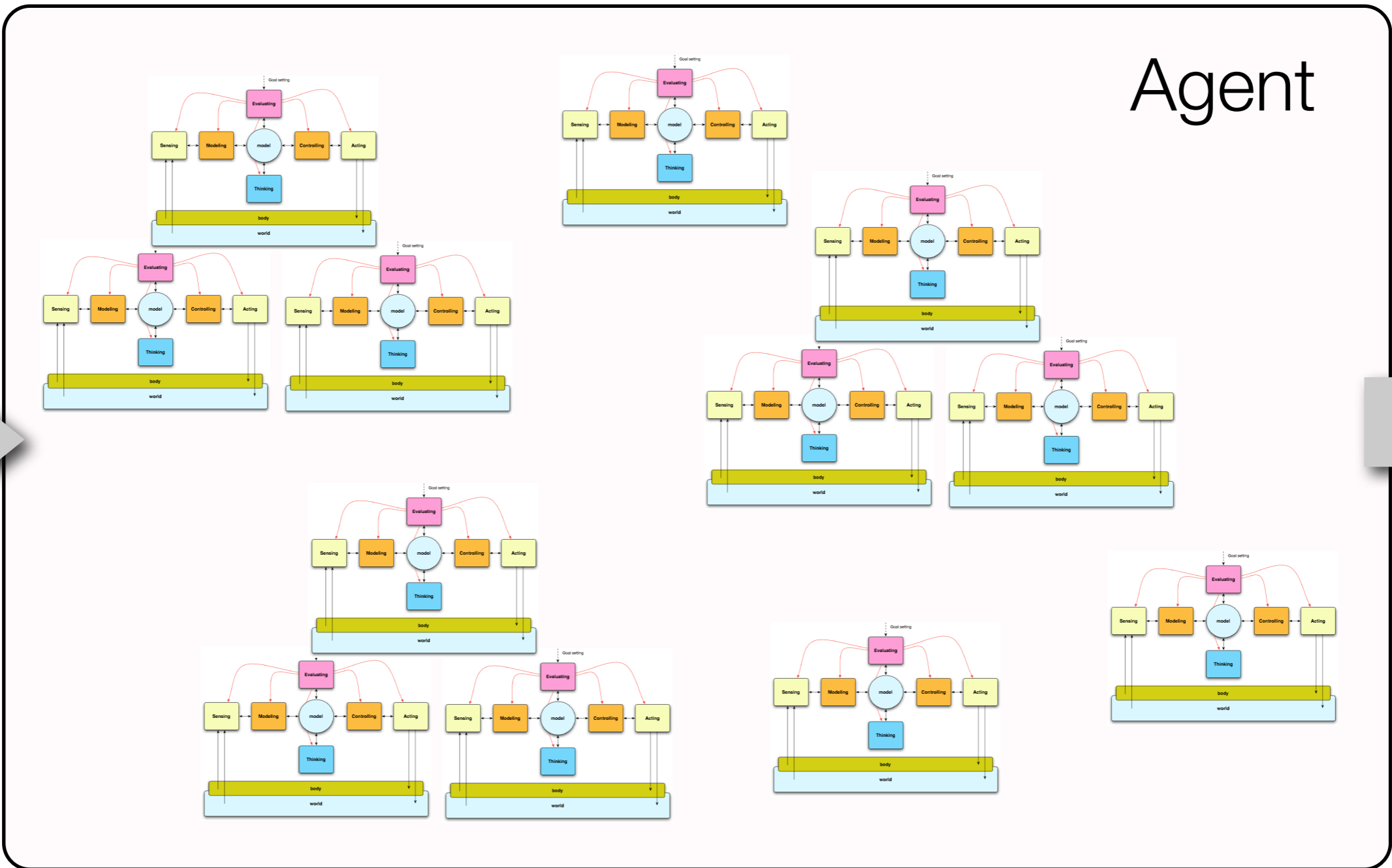


The Epistemic Loop



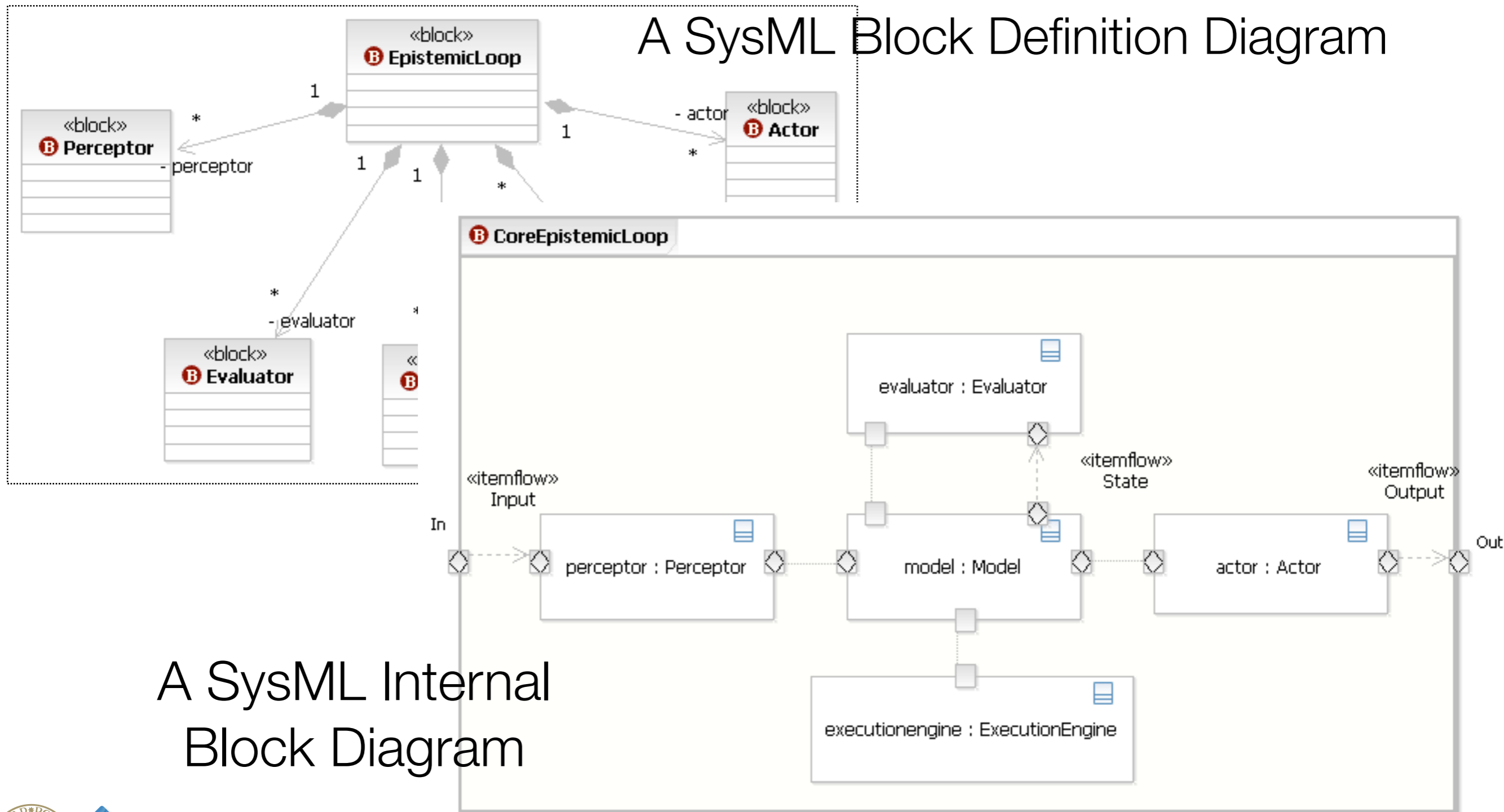
The Distributed Epistemic Loop

Agent



Epistemic Loop models

A SysML Block Definition Diagram



A SysML Internal Block Diagram

Model Structure

- The model is structured in several submodels:
 - The **ASys Ontology** model: a collection of core concepts on autonomous systems from the perspective of General Systems Theory
 - The **SOUL Architecture** model: a model of a self-aware autonomous agent architecture
 - The **Domain** models: models of domain-specific character (now working on **robotics** and **process control**)
 - The application models: concrete, final systems (**PCT,RCT**)

Summary

- The core objective of this approach is the development of **Reference Models of Consciousness**
- The SysML model will enable the **expression of the model-based control theory of consciousness in a formal enough language** as to minimise the problem of multiple interpretations
- The existence of the models in this form will also straightforward the development of systems based on this architecture
- The first public release will be available for **end of 2008**

Some References

- **OMG Systems Modeling Language Specification - Final Adopted Specification ptc/06-05-04 – 6 July 2006 – Final public version planned in April 2007.**
- **Laurent Balmelli. An Overview of the Systems Modeling Language for Products and Systems Development.** Journal of Object Technology. Vol. 6, No. 6, July-August 2007.
- UML SuperStructure specification: OMG
- MDA Specification: OMG
- Systems Engineering: INCOSE

Acknowledgements

- NOKIA / Pentti Haikonen
- European Commission through grant:

ICEA: Integrating Cognition, Emotion and Autonomy

- Spanish Government through grant:

C3: Conscious Cognitive Control

- Visit: www.iceaproject.eu



ICEA

Sommerhoff, 1990

“the various obstacles that confront those who seek to deal with consciousness in a physical language can be overcome if a strictly methodical approach is followed in which from the start all *analytical concepts are accurately defined* in physical terms.”

The End

*Systems, models and self-awareness
Toward a SysML model of consciousness*



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